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| Substitute for form 1449A/PTO INFORMATION DISCLOSURE STATEMENT BY APPLICANT(S) | | <i>Complete if Known</i> | |
| | | Application Number | 10/016,427 |
| | | Filing Date | December 10, 2001 |
| | | First Named Inventor | Kimon D. Roufas, et al. |
| | | Art Unit | 2877 |
| | | Examiner Name | Layla G. Lauchman |
| Sheet 1 of 1 | | Attorney Docket No. | D/A1131 (XERZ 2 00441) |

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| Examiner Initials* | Cite No. | Document No. Number-Kind Code (if known) | Publication/Issue Date MM-DD-YYYY | Name of Patentee or Applicant of Cited Document | Pages, Columns, Lines, Where Relevant Passages or Relevant Figures Appear |
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| | | Country Code-Number Kind Code (if known) | | | | |
| AM | | | | | | <input type="checkbox"/> |
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OTHER PRIOR ART - NON PATENT LITERATURE DOCUMENTS

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| Examiner Initials* | Cite No. | Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume/issue number(s), publisher, city and/or country where published | T |
| LL | AQ | Y. ZHANG, et al., <i>Sensor Computations in Modular Self Reconfigurable Robots</i> ; B. Siciliano and P. Dario (Eds.): Experimental Robotics VIII, STAR 5, pp. 276-286, 2003 © Springer-Verlag Berlin Heidelberg 2003. | <input type="checkbox"/> |
| LL | AR | M. YIM, et al., <i>PolyBot: a Modular Reconfigurable Robot</i> , Proceedings of the 2000 IEEE International Conference on Robotics & Automation, San Francisco, CA, April 2000, pp. 514-520 | <input type="checkbox"/> |
| | AS | | <input type="checkbox"/> |
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| Examiner Signature | | Date Considered | 9/1/04 |
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